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How to repair multi-agent plans without altering the satisfaction of the initial constraints

Nour El Houda Dehimi, Zakaria Tolba

Mathematics and Computer Science Department, ReLa(CS)2 Laboratory, University of Oum El Bouaghi, Algeria

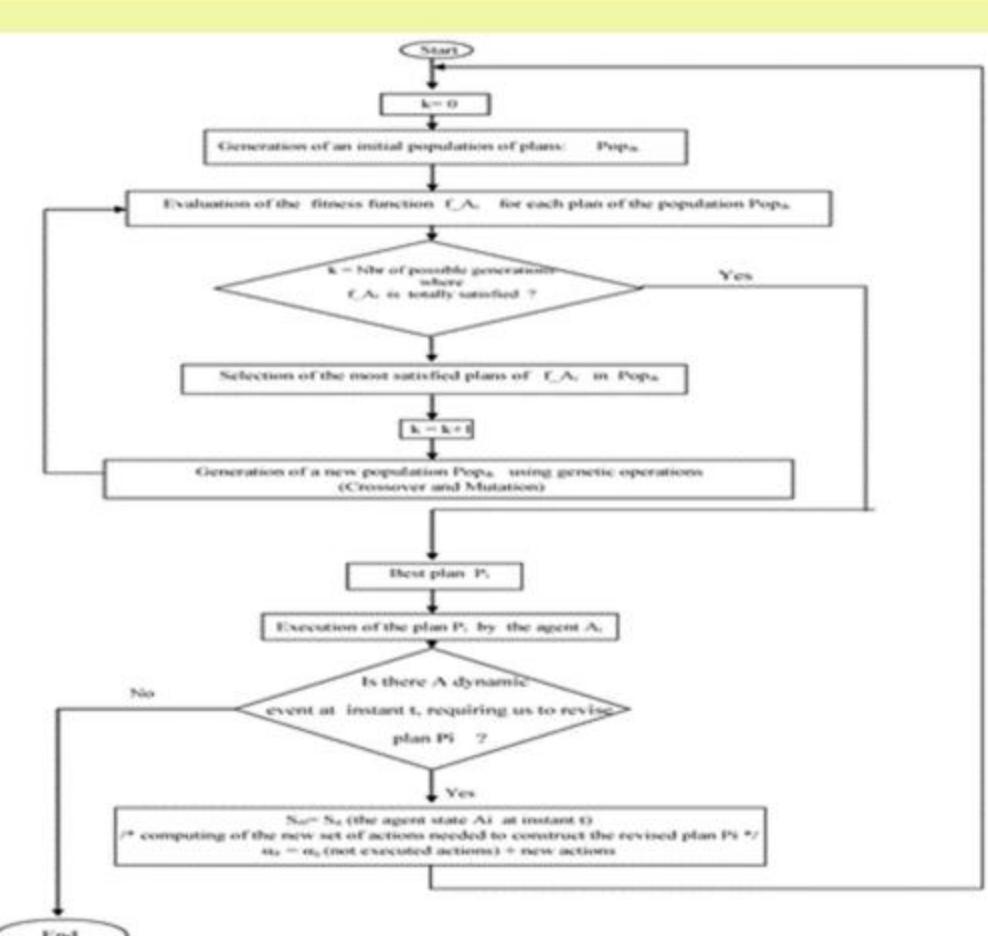
ABSTRACT

Our approach is to repair multi-agent plans, whenever there is a change in its set of actions to plan caused by the unpredictable changes of the environment. This, without altering the satisfaction of the initial constraints. The obtained results will be compared with the results obtained by the complete regeneration [1].

1. INTRODUCTION

h h h h h h h h h h h h
n h m h p h h h g w
g b . H g s
h o p i t h' s n w i
h w h H y h
h .
W , a h n i w p o h
h o b H . H , h g
m p i t h s w g h
h b h h h h h
t g h g g h h h
h .

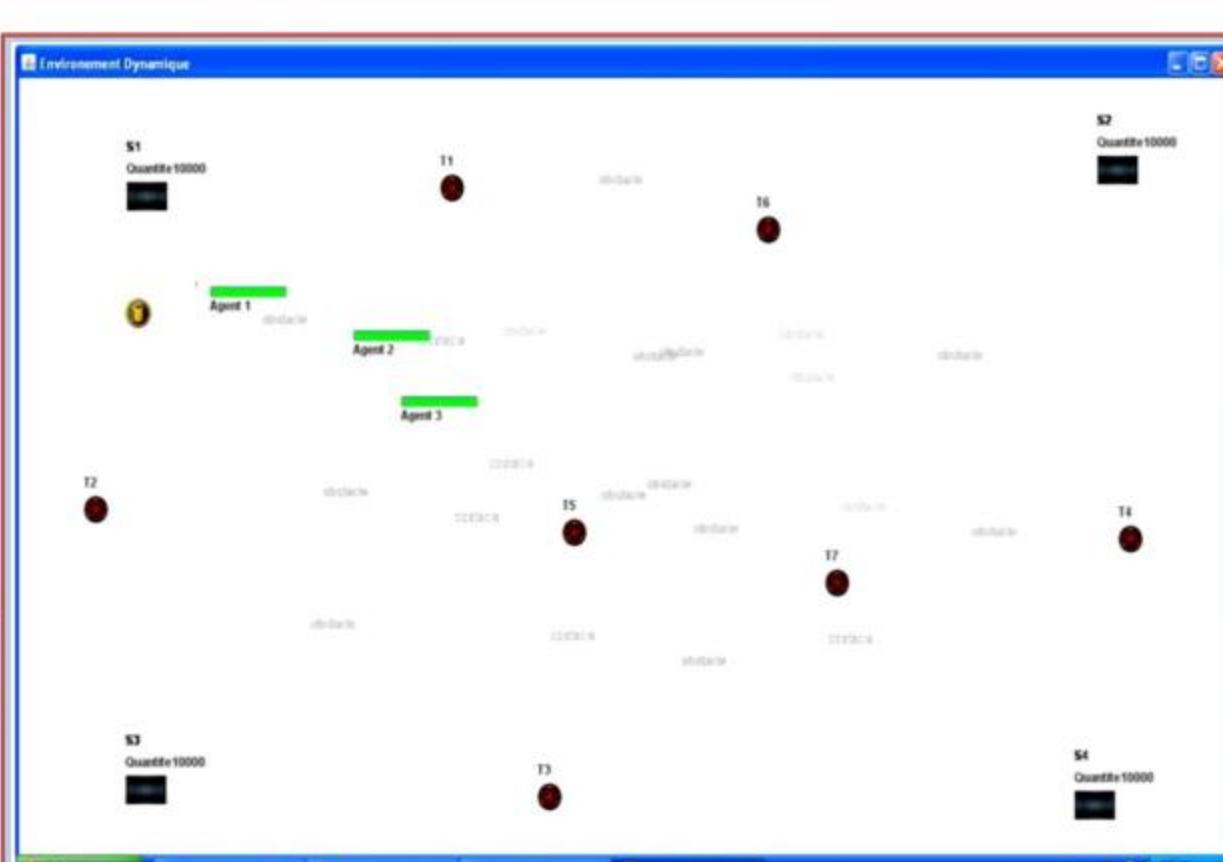
2. The proposed approach



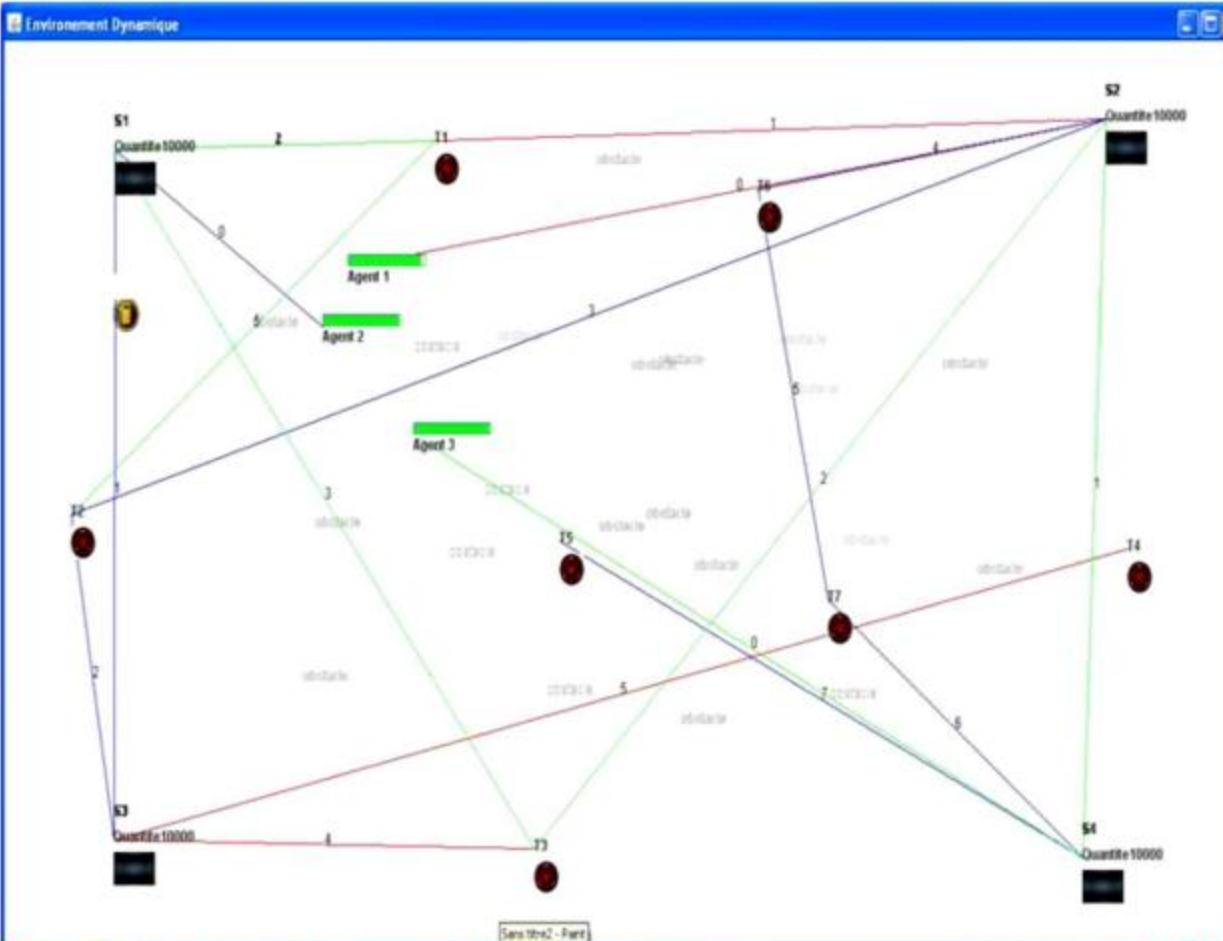
h h y w p h w h
h g h b y s t h
h o m j A s i n H
p S o a t s b h p a p
F . h h e h t n i s t
h g t n y t h b
h b a t s b h . E t s i s
h y h g h h F , h
h h j A , h p n w h
h s t S , h y b d h
h h a w a h y A
d y h t .

w g p h h g t n y
h m h . F f h : s
t in h h d h : s
p d h f h i H

3. The system state at the instant t_0



4. Representation of the initials plans



5. Repairing the initial plans

L s p h g h n f h
 h h y h g t n t a w
 h s d h n a w H
 p S5d h y h d f 6
 h w h h y t h
 b th :
 - R1 6 5A 5,T 1) Ø A 1F
 - R2 6 5A 5,T 9) Ø A 2F
 - R3 6 5A 5,T 8) Ø A 3F

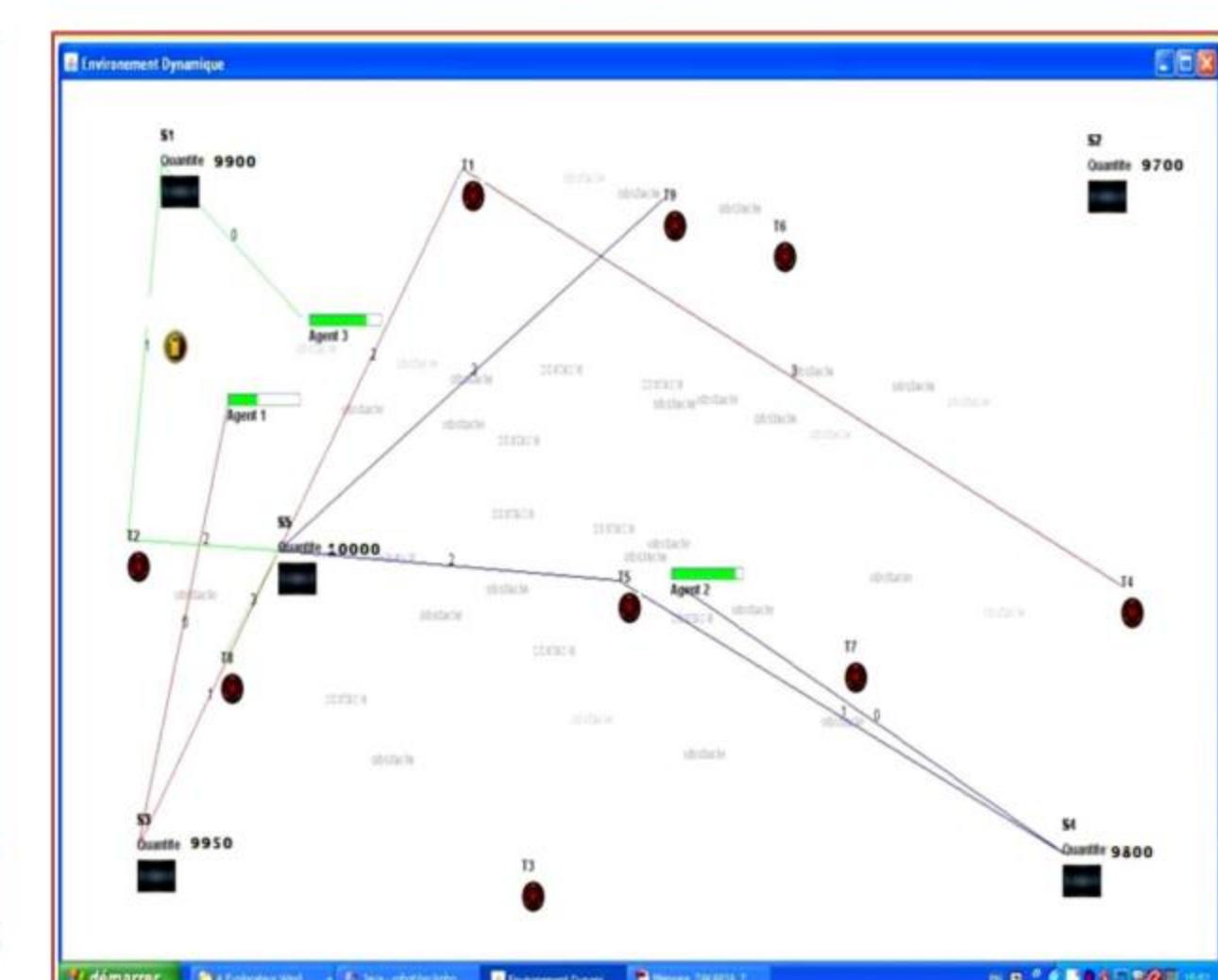
W e n h i g h l y p r o m i s e d . H o w
p r o p e r l y h a v e y o u i n d i c a t e d
h o w g r a t i f y i n g h o p e s p e c t i v e
p r o p e r t y i n t o d a y ' s
t a x i n g .

$P_{1t} = (\text{Move S3}, \text{false})(\text{Takes3}, \text{Article 3}, 50, \text{false})$ (**Move S5, false**)
(Takes5, Article 5, 400, false) (**Move T1, false**) (**DelevryT1, Article 5, 400, false**)
(Move T4, false) (**DelevryT4, Article 3, 50, false**)
 $F_{C1} = 7.323401357583406E-4$ $F_{C2} = 0.01$ $F_A = 6.381241907869489E-5$

$P_{2t} = (\text{Move S4}, \text{false})(\text{Takes4}, \text{Article 4}, 50, \text{false})$ (**Move T5, false**)
(DelevryT5, Article 4, 50, false) (**Move S5, false**) (**Takes5, Article 5, 100, false**) (**Move T9, false**) (**DelevryT9, Article 5, 100, false**)
 $F_{C1} = 4.165105495296216E-4$ $F_{C2} = 0.00961025641025641$ $F_A = 2.8483634339865544E-5$

$P_{3t} = (\text{Move T1}, \text{false})(\text{DelevryT1}, \text{Article 4}, 200, \text{false})$ (**Move S1, false**)
(TakesS1, Article 1, 150, false) (**Move T2, false**) (**DelevryT2, Article 1, 150, false**)
(Move S5, false) (**Takes5, Article 5, 100, false**)
(Move T8, false) (**DelevryT8, Article 5, 100, false**)

5. Representation of the repaired plans



6 CONCLUSIONS

H p b f k
g m :

- H n t b h g h y n
o n h h h t b b H y h
g y h g h n t b d h
h b n s m .

- H h a p n y i
b h g p .

- iA g o h e p f h
g b a w p i h g k
h m y h h h h n
t b p t w i d h
w p t b h h h

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Contact Information

DEHIMI Nour El Houda

Address

Tel: 05 58 15 20 00

Email: dehimi.nourelhouda@yahoo.fr

Web: www.yourwebsite.org